SuperMap iMobile

AR Map

SuperMap Software Co., Ltd.

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Your advice and suggestions are welcome!

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1. Overview

Augmented Reality (AR) is a new technology which can enhance real objects that exist in the real world, combine virtual and real worlds, and be perceived by humans.

Together with image recognition, real-time sensor, SLAM, GPS, and so on, SuperMap iMobile (hereinafter referred to as iMobile) can combine virtual and real worlds to solve the real problems in map recognition. Specific features include:

• Multiple AR Modes

Multiple AR display modes are provided to meet different requirements.

- Nearing: independent on maps, this mode can recognize, obtain, and display POI positions, distances, directions, attributes, and so on. It can be used in surface feature recognition, map browse, feature query, POI search, and so on.
- Following: combining real words and arrows, it can give directions of targets and position your destinations with your phone camera. It can be used in navigation.
- Infinite: this mode is used for browsing maps without dragging them. You can choose any one of them or combine them to get much better experiences.

• AR Project

Projection based on positions, directions, POI, and so on are supported. The targets which can be projected include images, text, maps, and videos.

• AR Map Gesture

When overlaying AR images and maps, you can manipulate your maps through gestures.

2. Modes Switching

You can switch them among the provided modes.



• Required codes:

Load library file: add jar libraries including com.supermap.ar.jar, com.supermap.data.jar, com.supermap.mapping.jar, and gson-2.2.2.jar and so libraries including libimb2d_v1000.so in the folder libs.



(2) Grant permissions: apart from the permissions required by iMobile, the following permissions should be granted:

```
<uses-permission android:name="android.permission.CAMERA"/>
<uses-permission android:name="android.permission.WAKE_LOCK"/>
<uses-permission
android:name="android.permission.RECEIVE_BOOT_COMPLETED"/>
<uses-permission android:name="android.permission.VIBRATE"/>
<uses-feature android:name="android.hardware.camera.any"/>
<uses-feature android:name="android.hardware.camera" android:required="true"/>
<uses-feature android:name="android.hardware.camera" android:required="true"/>
<uses-feature android:name="android.hardware.camera" android:required="true"/>
<uses-feature android:name="android.hardware.camera.autofocus"
android:required="true"/>
<uses-feature android:glEsVersion="0x00010100"/>
```

```
<uses-permission android:name="android.permission.INTERNET" />
(uses-permission android:name="android.permission.ACCESS_NETWORK_STATE" />
<uses-permission android:name="android.permission.ACCESS_WIFI_STATE" />
<uses-permission android:name="android.permission.ACCESS_FINE_LOCATION" />
(uses-permission android:name="android.permission.CHANGE_WIFI_STATE" />
<uses-permission android:name="android.permission.READ_EXTERNAL_STORAGE" />
<uses-permission android:name="android.permission.WRITE_EXTERNAL_STORAGE" />
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(uses-permission android:name="android.permission.VIBRATE"/>
(uses-feature android:name="android.hardware.camera.any"/>
(uses-feature android:name="android.hardware.camera" android:required="true"/>
(uses-feature android:name="android.hardware.camera.autofocus" android:required="true"/>
 uses-feature android:glEsVersion="0x00010100"/>
```

(3) Add controls: add the control ARControl2. Note: the control ARControl2 only can work in a landscape orientation.

<com.supermap.mapping.AR.ArControl2

```
android:id="@+id/arcontrol_supermap"
android:layout_width="match_parent"
android:layout_height="match_parent"
android:visibility="visible"/>
```

- Basic steps
- (1) Open a map: call functions in the classes Workspace and MapControl to open a workspace and a map.
- 2 Associate AR: associate ARControl2 with Mapcontrol and use the function setIsArmap() to set the AR map.

m Mapcontrol = m ArControl2.mapControl;

- m_Mapcontrol.getMap().setIsArmap(true); // Set a map to a AR map
 - (3) Set attributes relative to AR: call functions beginAR(), setARState(), setDatasetName(), setTileName(), and setRecordset() to set AR attributes.
- m_ArControl2.beginAR(); //starts the AR map mode
- m_ArControl2.setARState(true); //sets AR status
- m_ArControl2.setDatasetName("T7_REGION_INFO"); //Sets the POI dataset of the AR map
- m ArControl2.setTileName("FT NAME CN"); //Sets POI titles in the AR map
- m_ArControl2.setRecordset(mRecordsetAR); //Sets the record set
 - (4) Switch modes: call the function setARMode() in the class ArControl2 to switch modes.

m_ArControl2.setARMode(ARMode.AR_NORMAL); // Normal mode

m_ArControl2.setARMode(ARMode.AR_NEARING); // AR nearing mode

m_ArControl2.setARMode(ARMode.AR_FOLLOWING);//AR following mode

m_ArControl2.setARMode(ARMode.AR_INFINITE); //AR infinite mode

• Reference code:

//①Opens a map

Workspace mWorkspace = new Workspace();

WorkspaceConnectionInfo info = new WorkspaceConnectionInfo();

info.setServer(SDCARD + "SampleData/AR/supermapindoor.smwu"); //Sets the file name

info.setType(WorkspaceType.SMWU); //Sets the workspace type

boolean bOpen = mWorkspace.open(info);//Opens a workspace

if (bOpen){

//@Associates AR

```
m_ArControl2 = (ArControl2)findViewById(R.id.arcontrol_supermap);
```

m_Mapcontrol = m_ArControl2.mapControl;

m_Mapcontrol.getMap().setWorkspace(mWorkspace);//Sets the workspace which is associated with the map

String mapName = mWorkspace.getMaps().get(0);//Gets the name of the specified map

bOpen = m_Mapcontrol.getMap().open(mapName); //Opens a map

if (bOpen){

if (!m_Mapcontrol.getMap().lsArmap()) { //Whether it is an AR map

m_Mapcontrol.getMap().setIsArmap(true); //Sets it to an AR map

}

//③Sets related attributes of AR

m_ArControl2.beginAR(); //Starts the AR map

m_ArControl2.setARState(true); //Sets AR status

m_ArControl2.setDatasetName("T7_REGION_INFO"); //Sets the POI dataset of AR

map

m_ArControl2.setTileName("FT_NAME_CN"); //Sets the POI titles in the AR map

Datasource dtSource = mWorkspace.getDatasources().get(0);//Gets the specified datasource

if (dtSource != null) {

Dataset datasetDLTB = dtSource.getDatasets().get("T7_REGION_INFO"); //Gets the specified dataset

if (datasetDLTB != null) {

DatasetVector plDatasetVector = (DatasetVector) datasetDLTB;

Recordset mRecordsetAR = plDatasetVector.getRecordset(false,

CursorType.STATIC);//Gets the record set

m_ArControl2.setRecordset(mRecordsetAR); //Sets the record set

```
}
}else{
```

}

```
Toast.makeText(this,"Failed to open the map.",Toast.LENGTH_SHORT).show();
}
```

else {

Toast.makeText(this,"Failed to open the workspace.",Toast.LENGTH_SHORT).show();

//④Switches modes //Normal

public void buttonMap_Click(View view){

m_ArControl2.setARMode(ARMode.AR_NORMAL);

//AR nearing

public void buttonNearing_Click(View view){

```
m_ArControl2.setARMode(ARMode.AR_NEARING);
```

}

//AR following

public void buttonFollow_Click(View view){

m_ArControl2.setARMode(ARMode.AR_FOLLOWING);

//AR infinite

public void buttonnInfinite_Click(View view){

m_ArControl2.setARMode(ARMode.AR_INFINITE);

//Turns on the camera

```
public void buttonnOpenCamera_Click(View view){
```

```
m_ArControl2.showCamera();
```

//Turns off the camera

public void buttonnCloseCamera_Click(View view){

m_ArControl2.hideCamera();

}

//Turns on the map

public void buttonnOpenMap_Click(View view){

```
m_ArControl2.showMapView(true);
```

//Turns off the map

public void buttonnCloseMap_Click(View view){

m ArControl2.showMapView(false);

3. AR Map Gesture

}

AR map gestures allow you to operate your map freely on an AR scene.



Required codes:

Load library file: adds jar libraries including com.supermap.ar.jar, com.supermap.data.jar, com.supermap.mapping.jar, and gson-2.2.2.jar and the so library libimb2d_v1000.so in the folder libs.



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<uses-permission
android:name="android.permission.RECEIVE_BOOT_COMPLETED"/>
<uses-permission android:name="android.permission.VIBRATE"/>
<uses-feature android:name="android.hardware.camera.any"/>
<uses-feature android:name="android.hardware.camera" android:required="true"/>
```

```
<uses-feature android:name="android.hardware.camera.autofocus"
android:required="true"/>
```

<uses-feature android:glEsVersion="0x00010100"/>

```
<uses-permission android:name="android.permission.INTERNET" />
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<uses-permission android:name="android.permission.WRITE_EXTERNAL_STORAGE" />
<uses-permission android:name="android.permission.READ_PHONE_STATE" />
</uses-permission android:name="android.permission.READ_PHONE_STATE" />
</uses-permission.PEAD_PHONE_STATE" />
</uses-permission android:name="android.permission.READ_PHONE_STATE" />
</uses-permission android:name="android.permission.PE
```

```
<uses-permission android:name="android.permission.CAMERA"/>
<uses-permission android:name="android.permission.WAKE_LOCK"/>
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<uses-feature android:name="android.hardware.camera" android:required="true"/>
<uses-feature android:name="android.hardware.camera" android:required="true"/></uses-feature android:name="android:name="android:name="android:name="android:name="android.hardware.camera" android:required="true"/></uses-feature android:name="android:name="android:name="android:name="android:name="android:name="android.hardware.camera" android:name="android:name="android:name="
```

③ Add controls: MapView and CameraView.

```
<com.supermap.mapping.MapView
android:id="@+id/MapView"
android:layout_width="match_parent"
android:layout_height="match_parent"
android:visibility="visible">
</com.supermap.mapping.MapView>
<com.supermap.ar.CameraView
android:id="@+id/CameraView"
android:layout_width="match_parent"
android:layout_height="match_parent"
android:visibility="visible">
```

</com.supermap.ar.CameraView>

- Basic steps:
- Open a map. Call functions in the class Workspace, MapControl to open a workspace and a map.
- (2) Set map parameters. Call functions including setMapOverlay(), addOverlayMap(), enableRotateTouch(), enableSlantTouch(), and SetSlantAngle() to set map parameters.
- ③ Set the gesture listener. Calls the function setGestureDetector() to add the gesture listener.
- 4 Gestures. Add map operations including zooming, pitching, rotating, and so on.

• Reference code:

```
//(1)Opens a map
m Workspace = new Workspace();
WorkspaceConnectionInfo info = new WorkspaceConnectionInfo();
info.setServer(SDCARD + "/SampleData/AR/supermapindoor.smwu");
                                                                     //Sets the
  filename
info.setType(WorkspaceType.SMWU);
                                      //Set the workspace type
boolean bOpen = m_Workspace.open(info);
if (bOpen) {
  m MapView = (MapView) findViewById(R.id.MapView);
  m MapControl = m MapView.getMapControl();
                                                       //Gets the map control
  m MapControl.getMap().setWorkspace(m Workspace); //Gets the workspace which is
associated with the current map
  String mapName = m Workspace.getMaps().get(0);
                                                       //Gets the map name
  bOpen = m MapControl.getMap().open(mapName);
                                                       //Opens the specified map
 if (bOpen){
 //(2)Sets the map paramters
    m MapControl.getMap().setAlphaOverlay(true);
   m MapControl.setMapOverlay(true);
                                          //Sets the layers available to the map
    m MapControl.getMap().setCenter(new Point2D(116.512230,39.991812)); //Sets
     the center of the map
    m MapView.addOverlayMap(m MapControl);
                                                   //Adds the overlaid map
   m MapControl.enableRotateTouch(true);
                                                   //Allows to rotate a map
   m MapControl.enableSlantTouch(true);
                                                   //Allows to pitch a map
   m MapControl.getMap().setIsArmap(true);
                                                   //Sets the AR map mode
   m MapControl.getMap().setARMapAlpha(0.5f); //AR map transparency
    m MapControl.getMap().setARScrollEnable(true);
   m MapControl.getMap().SetSlantAngle(30);
                                                  //Sets the initial angle
   //(3)Sets the gesture listener
    m MapControl.setGestureDetector(new
GestureDetector(m_MapControl.getContext(), new
GestureDetector.OnGestureListener() {
      @Override
      public boolean onDown(MotionEvent e) {
        return false;
     }
      @Override
     public void onShowPress(MotionEvent e) {
     }
```

@Override

public boolean onSingleTapUp(MotionEvent e) {

return false;

}

@Override

```
public boolean onScroll(MotionEvent e1, MotionEvent e2, float distanceX, float
```

distanceY) {

//@Gesture operations

Rectangle2D viewBounds = m_MapControl.getMap().getViewBounds();//Gets the visible range of the current map

```
m_MapControl.getMap().setLockedViewBounds(viewBounds); //Sets the locked visible range of the map
```

m_MapControl.getMap().setViewBoundsLocked(false); //Sets the unlocked visible range of the map

```
if (e2.getPointerCount() > 1){
```

return true;

}

```
m_endDrawTime = System.currentTimeMillis();
```

```
if(m_endDrawTime - m_startDrawTime > 20)
```

{

```
if (Math.abs(distanceX) > Math.abs(distanceY)) {
```

```
m_rotateValueOfARMap += distanceX/3 ;
```

} else {

```
m_elevateValueOfARMap += distanceY * 5;
```

```
m\_MapControl.getMap().setARRotateCenter(m\_MapControl.getMap().get
```

Center());

```
m_MapControl.getMap().setARScrollValue((float)
```

```
m_elevateValueOfARMap);
```

```
}
```

```
m_MapControl.getMap().setAngle(m_MapControl.getMap().getAngle() +
distanceX/3);
```

}

```
m_startDrawTime = m_endDrawTime;
m_MapControl.getMap().refresh();
return true;
}
@Override
```

```
public void onLongPress(MotionEvent e) {
```

@Override
public boolean onFling(MotionEvent e1, MotionEvent e2, float velocityX, float
velocityY) {
 return false;
 }
 }));
 }else{
 Toast.makeText(this,"Failed to open the map.",Toast.LENGTH_SHORT).show();
 }
} else {
 Toast.makeText(this,"Failed to open the
workspace.",Toast.LENGTH_SHORT).show();

4. AR Project

}

Project POI or a map into an AR scene.



• Required codes:

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<uses-feature android:glEsVersion="0x00010100"/>

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<uses-permission android:name="android.permission.INTERNET" />
<uses-permission android:name="android.permission.ACCESS_NETWORK_STATE" />
<uses-permission android:name="android.permission.ACCESS_WIFI_STATE" />
<uses-permission android:name="android.permission.ACCESS_FINE_LOCATION" />
<uses-permission android:name="android.permission.CHANGE_WIFI_STATE" />
<uses-permission android:name="android.permission.READ_EXTERNAL_STORAGE" />
<uses-permission android:name="android.permission.WRITE_EXTERNAL_STORAGE" />
<uses-permission android:name="android.permission.READ_EXTERNAL_STORAGE" />
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```

③ Add controls: MapView and ArView. Add CameraView dynamically.

```
<com.supermap.mapping.MapView
android:id="@+id/MapView"
android:layout_width="match_parent"
android:layout_height="match_parent"
android:visibility="visible">
</com.supermap.mapping.MapView>
<com.supermap.ar.ArView
android:id="@+id/arView"
android:layout_width="match_parent"
android:layout_height="match_parent"
```

</com.supermap.ar.ArView>

• Basic steps:

- \bigcirc Parameter Settings
- (1). Set the drawing mode. Call the function

ARRendererInfoUtil.saveARRendererMode() and set the drawing mode to

MODE_PROJECTION

ARRendererInfoUtil.saveARRendererMode(**this**,ARRendererInfoUtil.**MODE_PROJECT ION**);

- (2). Add the camera layout. Add CameraView to the layout.
- (3). Initialize and register the sensor. Call the function registerListener() to register the magnetic field sensor and the acceleration sensor.
- (4). Initialize ARView. Add the functions setOnClickArObjectListener() and setArViewAdapter().
- (5). Create augmented reality world and associate ARView. Call the function setWorld() of the class ArView.
- (6). Initialize the map and associate ARView. Call functions of the classes Workspace and MapControl to open the workspace and the map. Call the functions setMapView() and setMapcontrol() of the class ArView to associate ARView with the map.
- (7). Initialize the progress bar. This parameter is optional. Control the height of the observation point, the size and the maximum visible range of the projected target.

m_ArView.setHead((float)progress); //Sets the height of the observation point m_ArView.setDistanceFactor((float)progress/10); //Sets the size of the projected point (POI/map)

- m_ArView.setMaxDistanceToRender(progress); //Sets the maximum visible range
 - (8). Set smoothing value. How much the smoothing value is depends on the

device. The smaller the value is, the slower the AR scene moves.

LowPassFilter.*ALPHA* = 0.038f;

- (9). Add the map refreshing Timer. The parameter is used for delaying map refreshing thereby saving resources when projecting a map.
- POI Projection. Create a new xml layout for POI display. You can customize content.
- (1). Create a GeoObject.
- (2). Set the latitude and longitude of GeoObject.
- (3). Set the name of GeoObject.
- (4). Set how to display GeoObject. After that, call the function

storeArObjectViewAndUri () of the class ArView to save the setting to the

layout.

m_ArView.storeArObjectViewAndUri(poiView,tempArObject);

(5). Add to an AR scene. Call the method addArObject() of the class World.

m_World.addArObject(tempArObject);

③ Map Projection

- (1). Add a map and set it visible.
- (2). Set the latitude and longitude of GeoObject.
- (3). Set the displaying style. After that, call the function

storeArObjectViewAndUri() of the class ArView to save the setting to the

layout.

m_ArView.storeArObjectViewAndUri(view,tempArObject);

(4). Add to an AR scene. Call the method addArObject() of the class World.

m_World.addArObject(tempArObject);

• Reference codes:

//①Sets the drawing mode which must be put before setContentView

ARRendererInfoUtil.saveARRendererMode(this,ARRendererInfoUtil.MODE_PROJECTI ON);

setContentView(R.layout.activity_main);

//②Adds the camera layout

AddCarmeraView();

//③Initializes and registers the sensor

InitAndRegisterSensor();

//@Initializes ARView

InitARView();

//⑤Creates the augmented reality world and associates ARView

InitARWord();

//⑥Initializes the map and associates ARView

InitMap();

//⑦Initializes the progress bar (optional)

initSeekbar();

//⑧Sets the smoothing value

initLowPassFilter();

// (9) When projecting a map, delay the map refreshing to save resources.

new Handler().postDelayed(new Runnable(){

public void run(){

setTimer();

}

}, <mark>3000</mark>);

//②Add the camera to a layout

public void AddCarmeraView(){

RelativeLayout mRelativeLayout = findViewById(R.id.relativeAR);

FrameLayout.LayoutParams cameraViewParams = new

FrameLayout.LayoutParams(ViewGroup.LayoutParams.MATCH_PARENT,

ViewGroup.LayoutParams.MATCH_PARENT);

CameraView mArCameraView = new CameraView(this);

mRelativeLayout.addView(mArCameraView, 0, cameraViewParams);

}

//③Initialize and register the sensor

```
public void InitAndRegisterSensor(){
    m_SensorManager = (SensorManager)
getSystemService(Context.SENSOR_SERVICE);
    m_SensorEventListener = new SensorEventListener() {
    @Override
    public void onSensorChanged(SensorEvent event) {
    }
}
```

@Override

public void onAccuracyChanged(Sensor sensor, int accuracy) {

};

}

m_SensorManager.registerListener(m_SensorEventListener, m_magneticSensor, SensorManager.SENSOR_DELAY_NORMAL);

m_SensorManager.registerListener(m_SensorEventListener,

m_accelerometerSensor, SensorManager.SENSOR_DELAY_NORMAL);

m_magneticSensor =

m_SensorManager.getDefaultSensor(Sensor.TYPE_MAGNETIC_FIELD); //Magnetic field sensor

m_accelerometerSensor =

m_SensorManager.getDefaultSensor(Sensor.TYPE_ACCELEROMETER);//Acceleration sensor

}

//@Initializes ARView

public void InitARView(){

```
m_listARObjects = Collections.synchronizedList(new ArrayList < ArObject > ());
```

```
m_ArView = findViewById(R.id.arView);
```

```
m_ArView.setOnClickArObjectListener(new OnClickArObjectListener() {
```

@Override

public void onClickArObject(ArrayList < ArObject > arrayList) {//Controls whether to display the pop-up dialog box

```
if (arrayList.size() = = 0) {
      return;
    }
    ArObject arObject = arrayList.get(0);
    if (m listARObjects.contains(arObject)) {
      m listARObjects.remove(arObject);
    } else {
      m listARObjects.add(arObject);
    }
  }
});
m ArView.setDistanceFactor(0.8f); //Sets the default size of POI
m ArView.setArViewAdapter(new ArViewAdapter(this) {//Sets an adapter to make it
          available that drawing a view on the top of the AR view
  @Override
  public View getView(ArObject arObject, View view, ViewGroup viewGroup) {
```

```
if (!m listARObjects.contains(arObject)) {
        return null;
      }
      LayoutInflater inflater = (LayoutInflater)
MainActivity.this.getSystemService(Context.LAYOUT INFLATER SERVICE);
      if (view == null) {
        view = inflater.inflate(R.layout.ar object view, null);
      }
      arObject.setIsShow(true);
      TextView textView = (TextView) view.findViewById(R.id.titleTextView);
      textView.setText(arObject.getName());
      Button button = (Button) view.findViewById(R.id.button);
      button.setOnClickListener(new View.OnClickListener() {
        @Override
        public void onClick(View v) {
        }
      });
      button.setText("Azimuth: " + arObject.getAngle().z);
      button.setTag(arObject.getName());
      setPosition(arObject.getScreenPositionTopRight());
      return view;
   }
 });
}
  //⑤Creates the augmented reality world and associates ARView
public void InitARWord(){
    m World = new World(this);
    m World.setGeoPosition(23.626947,120.811991); //Sets the current position
    m ArView.setWorld(m World);
                                     //Associates the AR scene
}
    //⑥Initializes the map and associates ARView
public void InitMap(){
  Workspace workspace = new Workspace();
  WorkspaceConnectionInfo info = new WorkspaceConnectionInfo();
  info.setServer(sdcard+"/SampleData/Taiwan/Taiwan.smwu");
  info.setType(WorkspaceType.SMWU);
```

```
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```

```
if (workspace.open(info)) {
    m MapView = findViewById(R.id.mapView);
    m MapControl = m MapView.getMapControl();
    m MapControl.getMap().setWorkspace(workspace);
    String mapName = workspace.getMaps().get(2);
    if (m MapControl.getMap().open(mapName)) {
       m MapControl.getMap().setAlphaOverlay(true);
       m MapControl.setMapOverlay(true);
       m ArView.setMapView(m MapView);
       m ArView.setMapcontrol(m MapControl);
       m MapControl.getMap().setIsArmap(true);//Sets to an AR map
       m MapControl.getMap().setARMapType(5); //Sets the type of ARMap to POI view
mode
       m ArView.getMapChangedMatrix(m transformMatirx,m projectionMatrix);
       m MapControl.getMap().setTransformMatrix(m transformMatirx);
       m MapControl.getMap().setProjectMatrix(m projectionMatrix);
       m MapControl.getMap().refresh();
     }
      else{
        Toast.makeText(this,"Failed to open the
map.",Toast.LENGTH SHORT).show();
        return;
     }
   }
    else{
      Toast.makeText(this,"Failed to open the
workspace.",Toast.LENGTH SHORT).show();
      return;
   }
}
    //(7)Initializes the progress bar
public void initSeekbar() {
  m ArView.setMaxDistanceToRender(8);
    //Sets the height of the observation point
  m SeekHeadFactor = (SeekBar) findViewById(R.id.seekHead);
  m SeekHeadFactor.setMax(100);
  m SeekHeadFactor.setOnSeekBarChangeListener(new
```

```
SeekBar.OnSeekBarChangeListener() {
```

@Override public void onProgressChanged(SeekBar seekBar, int progress, boolean fromUser) { if(seekBar == m SeekHeadFactor) { m ArView.setHead((float)progress); //Sets the height of the observation point } } @Override public void onStartTrackingTouch(SeekBar seekBar) { } @Override public void onStopTrackingTouch(SeekBar seekBar) { } }); //Sets the size of the projected target m SeekDistanceFactor = (SeekBar) findViewById(R.id.seekFactorRender); m SeekDistanceFactor.setMax(100); m SeekDistanceFactor.setProgress(20); m SeekDistanceFactor.setOnSeekBarChangeListener(new

SeekBar.OnSeekBarChangeListener() {

@Override

public void onProgressChanged(SeekBar seekBar, int progress, boolean

fromUser) {

```
if(seekBar == m_SeekDistanceFactor) {
```

m_ArView.setDistanceFactor((float)progress/10); //Sets the visible size of the projected target

```
}
}
@Override
public void onStartTrackingTouch(SeekBar seekBar) {
}
@Override
public void onStopTrackingTouch(SeekBar seekBar) {
}
```

});

//Sets the maximum visible range

m_SeekMaxRender = (SeekBar) findViewById(R.id.seekMaxRender);

```
m_SeekMaxRender.setMax(100);
```

```
m SeekMaxRender.setOnSeekBarChangeListener(new
SeekBar.OnSeekBarChangeListener() {
    @Override
    public void onProgressChanged(SeekBar seekBar, int progress, boolean
fromUser) {
     if(seekBar == m SeekMaxRender) {
        m_ArView.setMaxDistanceToRender(progress); //Sets the maximum visible
range
     }
   }
    @Override
    public void onStartTrackingTouch(SeekBar seekBar) {
   }
    @Override
    public void onStopTrackingTouch(SeekBar seekBar) {
   }
 });
   //⑧Sets the smoothing value
public void initLowPassFilter(){
    LowPassFilter.ALPHA = 0.038f;//How much the smoothing value is depends on the device.
}
   //POI projection
public void btnPOIProjection onClick(View view){
  Point3D intersectionPoint =
m ArView.getIntersectionPoint(getResources().getDisplayMetrics().widthPixels/2,get
Resources().getDisplayMetrics().heightPixels/2);
  if(intersectionPoint != null){
    //(1)Creates a GeoObject(POI) and give it an id
    GeoObject tempArObject = new GeoObject(System.currentTimeMillis());
    //②Sets the latitude and longitude of the GeoObject(POI)
    tempArObject.setGeoPosition(m World.getLatitude()+intersectionPoint.y/10781
7.51838439942D,m World.getLongitude()+intersectionPoint.x/107817.51838439942
D,m World.getAltitude()+intersectionPoint.z/107817.51838439942D);
    //③Sets the name of the GeoObject(POI)
    tempArObject.setName("Screen Poi");
    DecimalFormat df = new DecimalFormat("0.00");
```

```
tempArObject.setDistanceFromUser(Double.parseDouble(df.format(20)));//Adds
the distance information
    //④Sets the display style of the GeoObject(POI)
    View poiView = getLayoutInflater().inflate(R.layout.static ar object view, null);
    Button btnPOIName = (Button)poiView.findViewById(R.id.btn poi name);
    btnPOIName.setText(tempArObject.getName());
    Button btnPOIDistance = (Button)poiView.findViewById(R.id.btn_poi_distance);
    btnPOIDistance.setText(""+tempArObject.getDistanceFromUser()+"m");
    m ArView.storeArObjectViewAndUri(poiView,tempArObject); //Saves UI according
to the layout
   //(5)Adds to an AR scene
    m World.addArObject(tempArObject);
 }
}
    //Map projection
public void btnMapProjection onClick(View view){
  List < ArObjectList > arObjectList = m World.getArObjectLists();
  ArObjectList localARObjectList = arObjectList.get(0);
 for(int i = 0;i<localARObjectList.size();i++){</pre>
    if(localARObjectList.get(i).getId() == ArView.PROJECTION MAP ID){
       m World.remove(localARObjectList.get(i));
   }
 }
    //(1)Adds a layer
 int layersNum = m MapControl.getMap().getLayers().getCount()
 for(int i = 0;i<layersNum;i++){</pre>
     m MapControl.getMap().getLayers().get(i).setVisible(true);
 }
  Point3D point =
m ArView.getIntersectionPoint(getResources().getDisplayMetrics().widthPixels/2,get
Resources().getDisplayMetrics().heightPixels/2);
    if(point != null){
   //②Sets the latitude and longitude of the GeoObject(POI)
    GeoObject tempArObject = new GeoObject(ArView.PROJECTION MAP ID);
    tempArObject.setGeoPosition(m World.getLatitude()+point.y,m World.getLongi
tude()+point.x,m World.getAltitude()+point.z);
   //(3)Sets the display style
    tempArObject.setName("");
```

```
DecimalFormat df = new DecimalFormat("0.00");
   tempArObject.setDistanceFromUser(Double.parseDouble(df.format(20)));//
   Adds the distance information
    m ArView.storeArObjectViewAndUri(view,tempArObject);//Adds to the AR scene
   m World.addArObject(tempArObject);
 }
ł
private void setTimer(){
   Message message = m_handler.obtainMessage(TIMER);
    m handler.sendMessageDelayed(message, 1000);
private Handler m handler = new Handler(){
  @Override
  public void handleMessage(Message msg) {
   super.handleMessage(msg);
   switch (msg.what){
      case TIMER:
        m ArView.getMapChangedMatrix(m transformMatirx,m projectionMatrix);
        m MapControl.getMap().setTransformMatrix(m transformMatirx);
        m MapControl.getMap().setProjectMatrix(m projectionMatrix);
        m MapControl.getMap().refresh();
        Message message = m handler.obtainMessage(TIMER);
        m handler.sendMessageDelayed(message, 200);
      break;
      default:
      break:
     }
   }
};
@Override
protected void onResume() {
    super.onResume();
    m SensorManager.registerListener(m SensorEventListener, m magneticSensor,
SensorManager.SENSOR DELAY NORMAL);
    m SensorManager.registerListener(m SensorEventListener,
```

```
m_accelerometerSensor, SensorManager.SENSOR_DELAY_NORMAL);
```

}

@Override

}

protected void onPause() {

super.onPause();

m_SensorManager.unregisterListener(m_SensorEventListener);